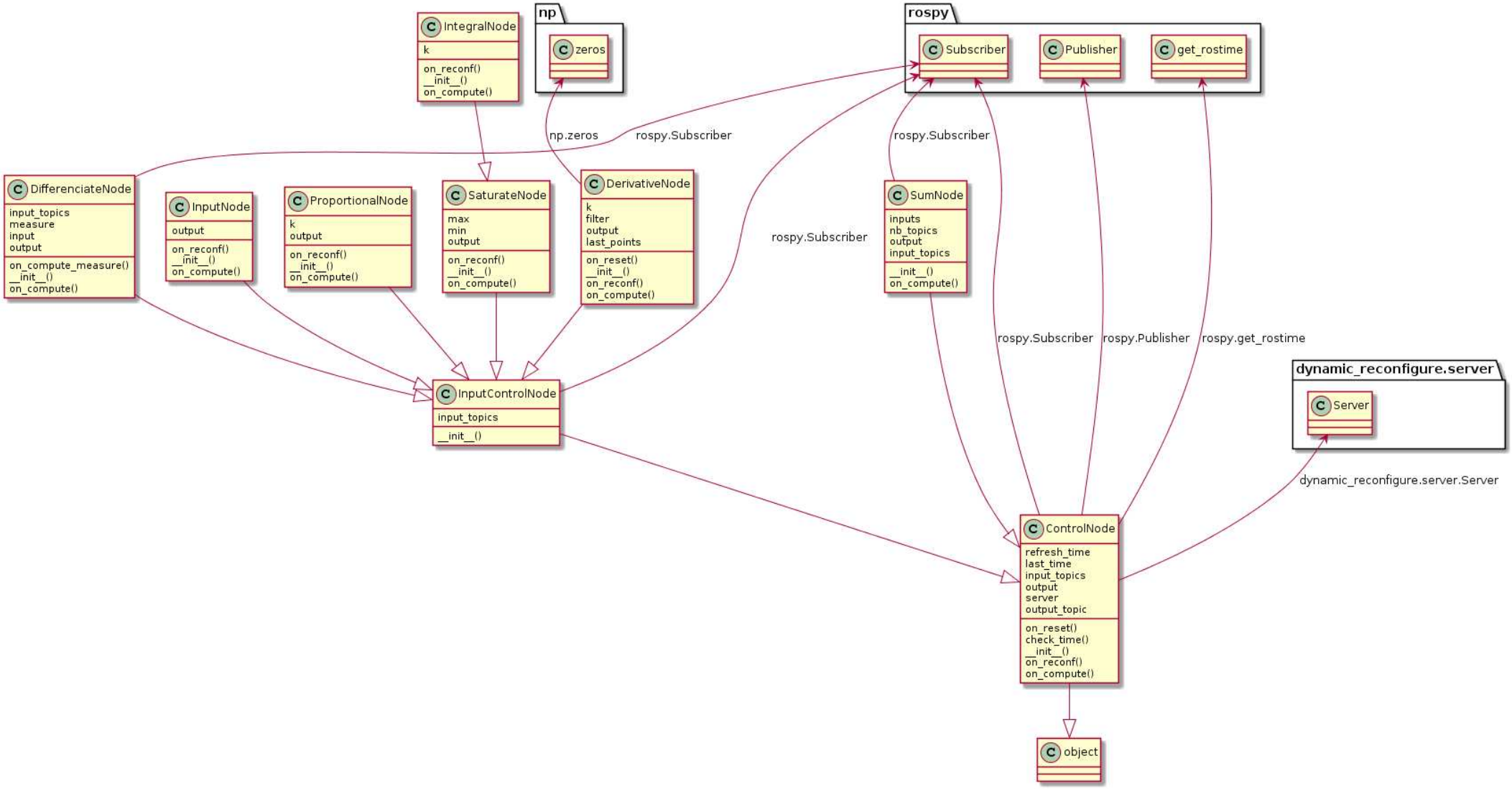
np
zeros
rospy
Subscriber
Publisher
get_rostime
IntegralNode
k
on_reconf()
__init__()
on_compute()
np.zeros
rospy.Subscriber
rospy.Subscriber
DifferenciateNode
input_topics
measure
input
output
on_compute_measure()
__init__()
on_compute()
InputNode
output
on_reconf()
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on_compute()
ProportionalNode
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on_reconf()
__init__()
on_compute()
SaturateNode
max
min
output
on_reconf()
__init__()
on_compute()
DerivativeNode
k
filter
output
last_points
on_reset()
__init__()
on_reconf()
on_compute()
rospy.Subscriber
SumNode
inputs
nb_topics
output
input_topics
__init__()
on_compute()
rospy.Subscriber
rospy.Publisher
rospy.get_rostime
dynamic_reconfigure.server
Server
InputControlNode
input_topics
__init__()
dynamic_reconfigure.server.Server
ControlNode
refresh_time
last_time
input_topics
output
server
output_topic
on_reset()
check_time()
__init__()
on_reconf()
on_compute()
object